



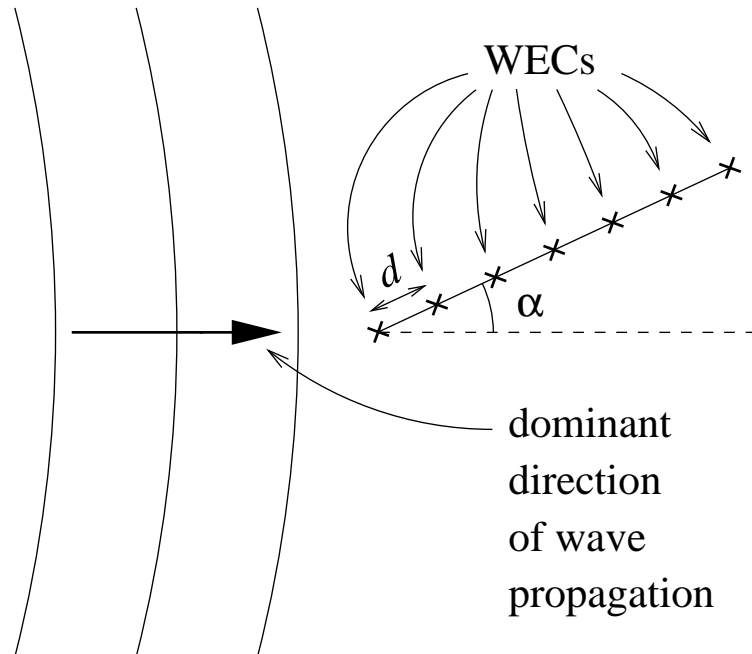
Time Domain Modelling of Array Interaction

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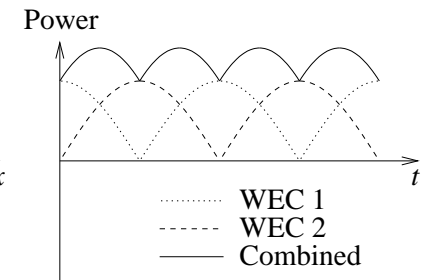
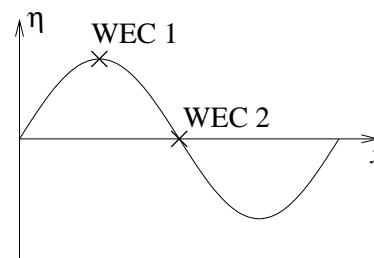
Initial Array Modelling



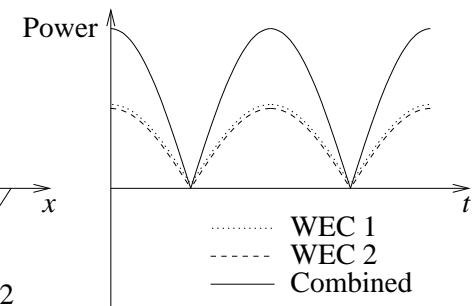
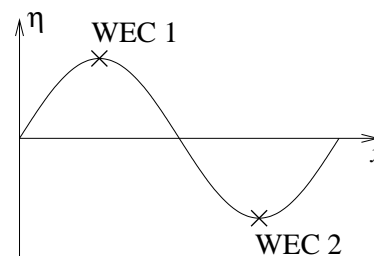
Time domain model of an array of **individual** buoys with **aggregated** power output – adjustable spacing, wave direction and spectra.



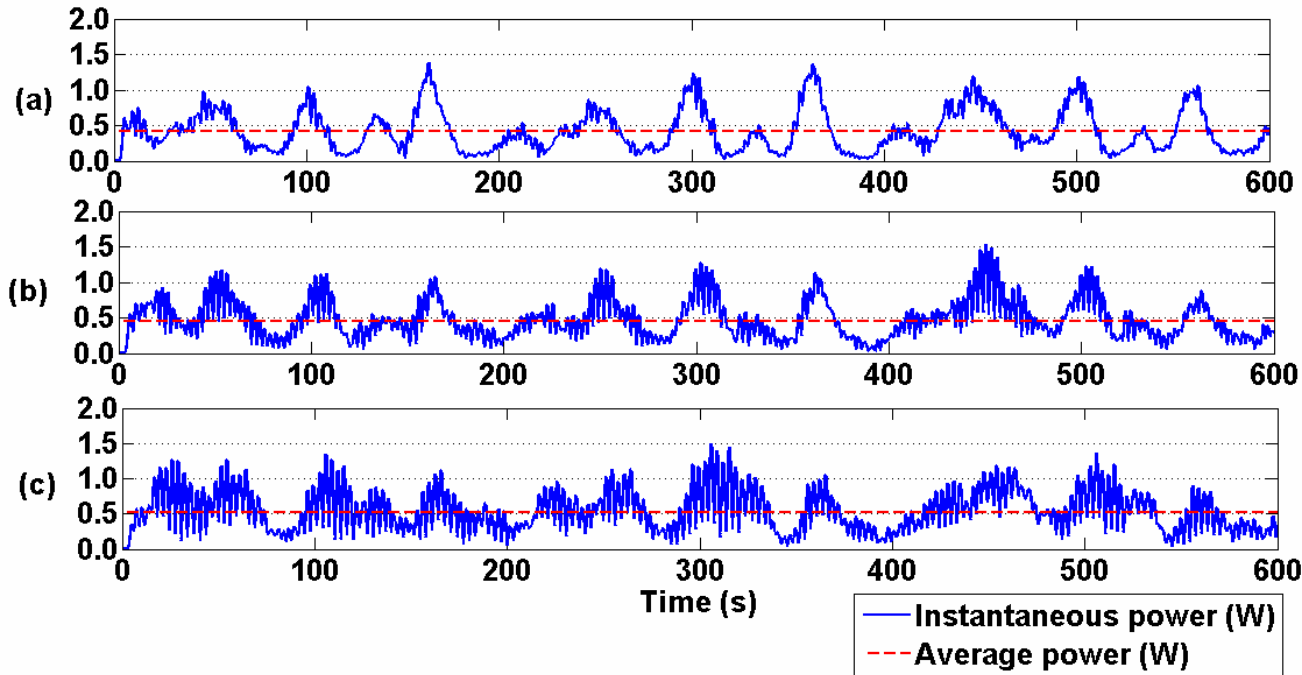
0.25λ Spacing



0.5λ Spacing



Aggregate Mechanical Power from Array in Irregular Seas



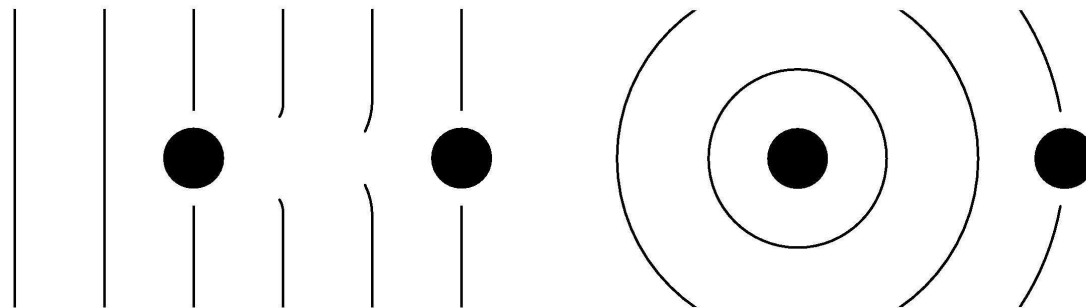
(a) $d = 0.25\lambda_{\text{peak}}$

(b) $d = 0.375\lambda_{\text{peak}}$

(c) $d = 0.5\lambda_{\text{peak}}$

Limitations:

No hydrodynamic coupling between buoys ... neither



Diffraction, nor ... Radiation

Time Domain Array Model with **All** Hydrodynamic Interactions



Most existing array models are frequency domain.

To fit into an overall model, including control systems, we needed to develop a time domain model.

The time domain model being developed:

- Takes hydrodynamic coefficients from one frequency domain simulation.
- Embodies them in fully mathematically and physically rigorous equations of motion.
- Solves equations simply and quickly within time-steps for control simulation.

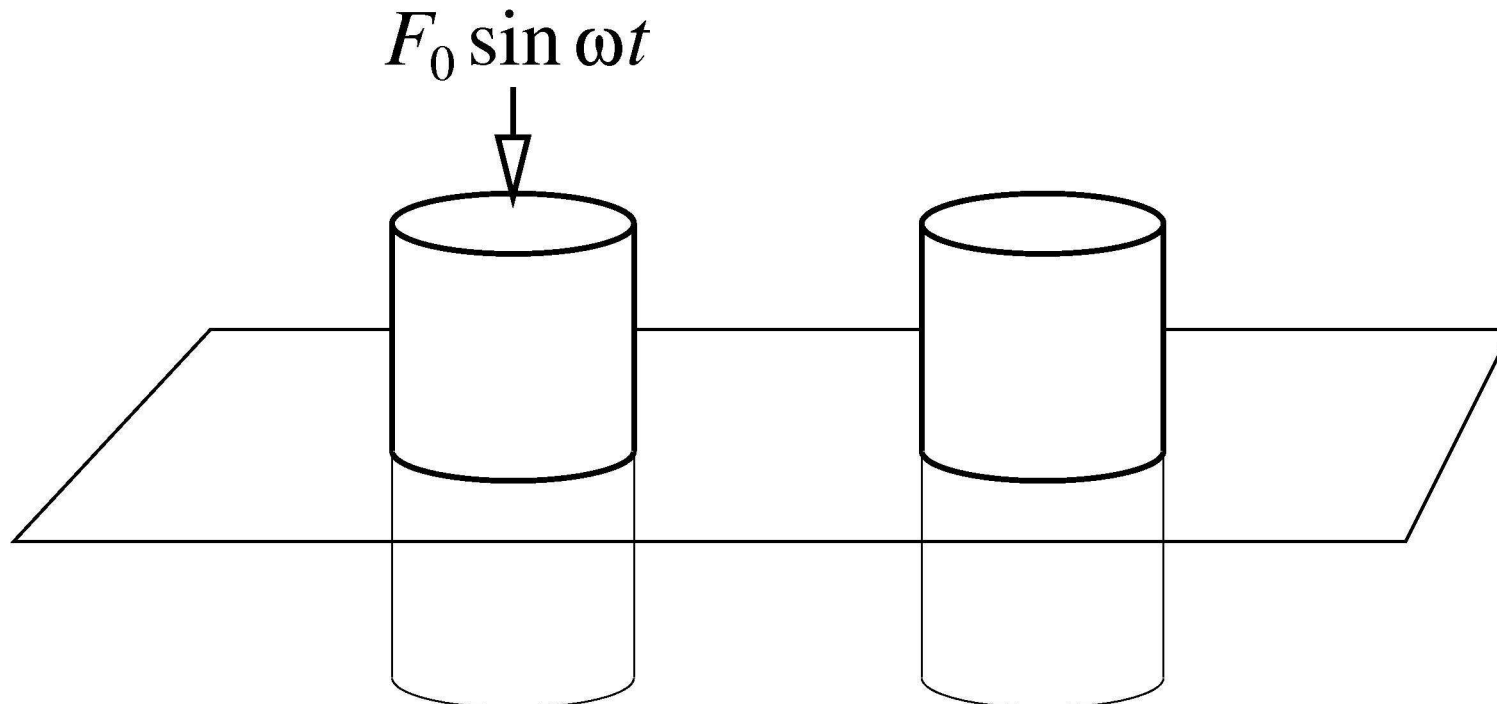
Advantages:

- Allows the implementation and testing of control schemes and algorithms.
- Can model transients.
- Can be extended to include non-linearities.
- Can explore coordinated control algorithms across array.
- Will be incorporated into the wave-to-wire model.

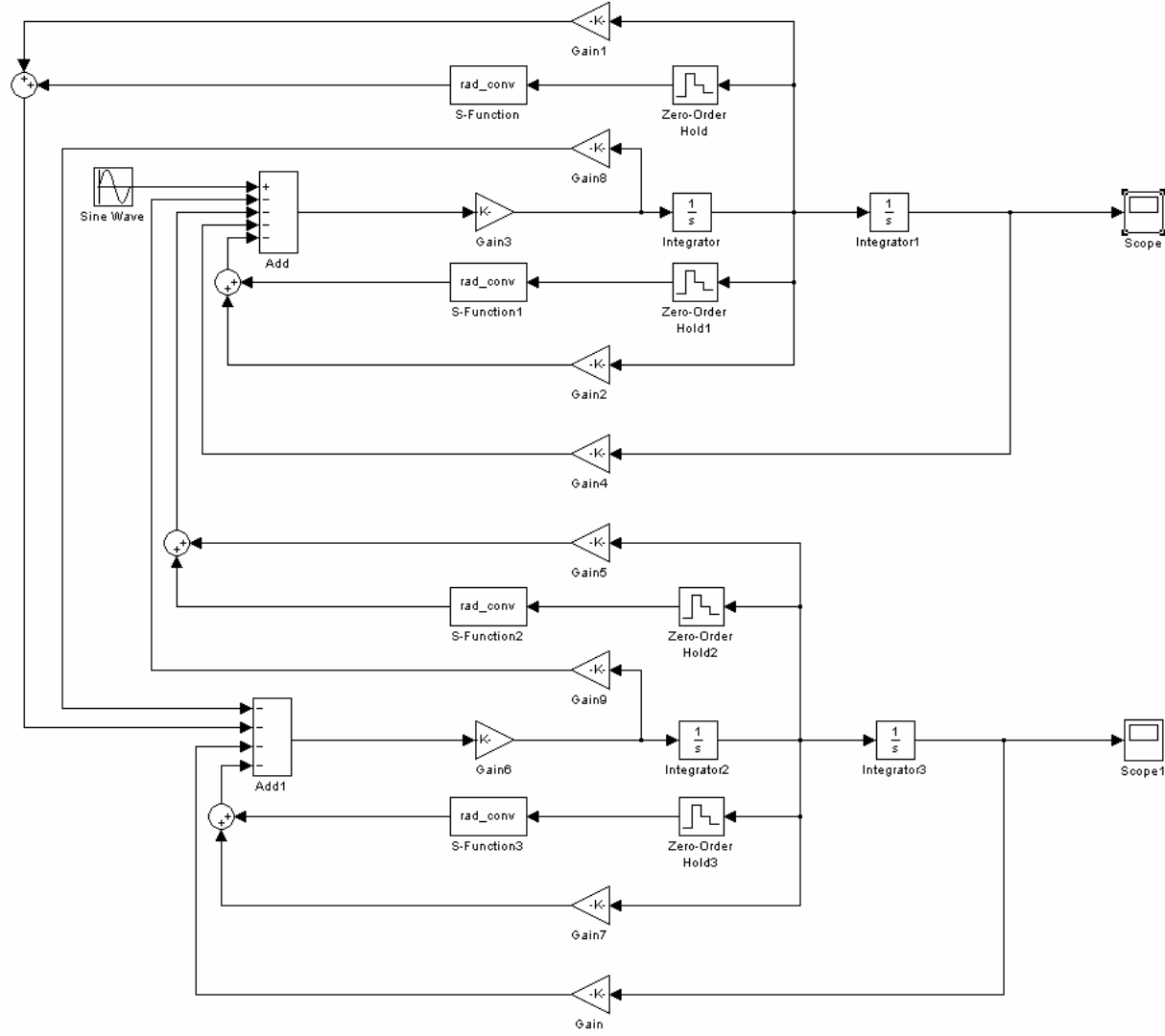
Interaction



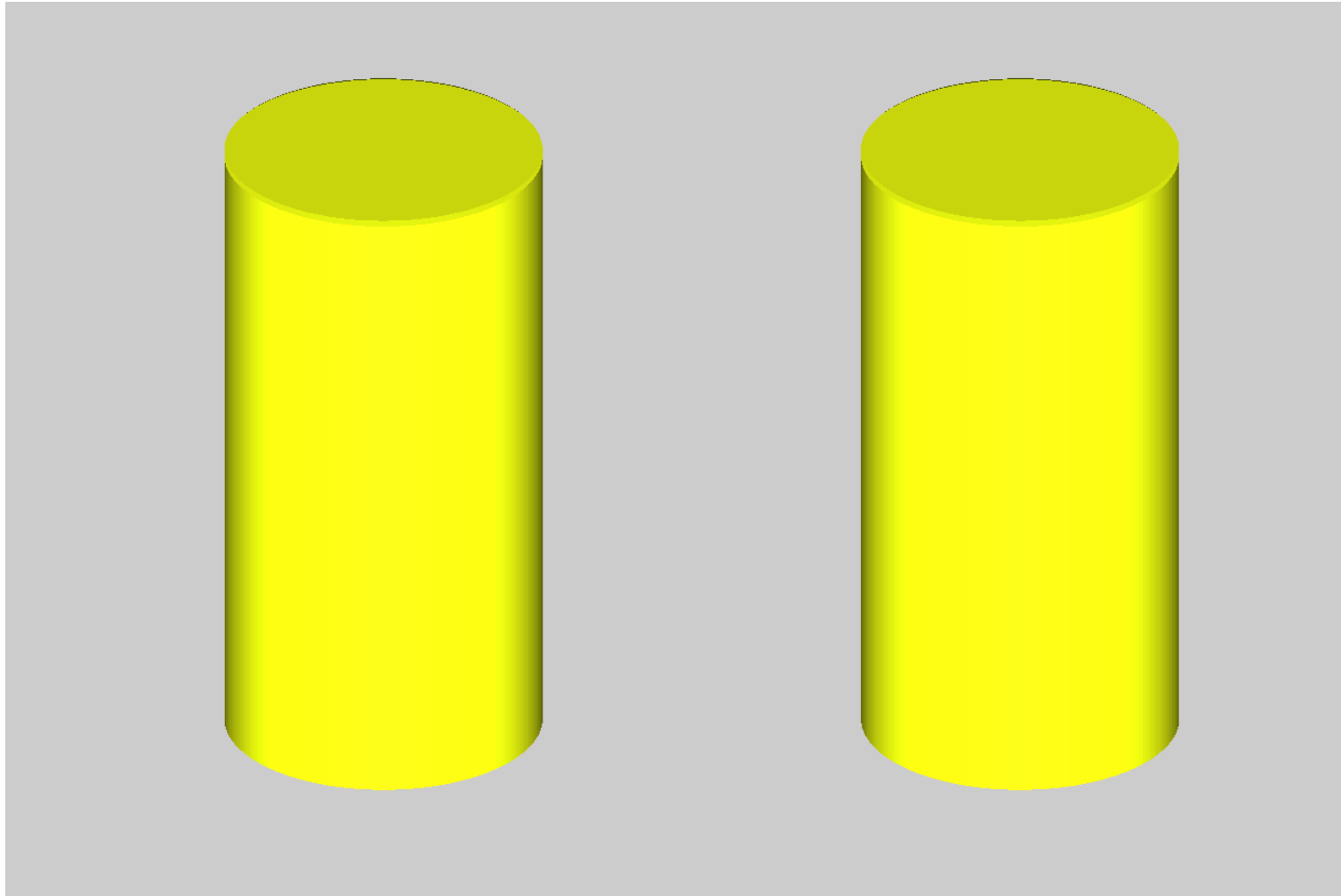
- We can have any number and shape of buoys (or other forms) in an array, with each moving in up to 6 degrees of freedom, but
- Begin with two freely-floating cylinders, constrained to move in heave:



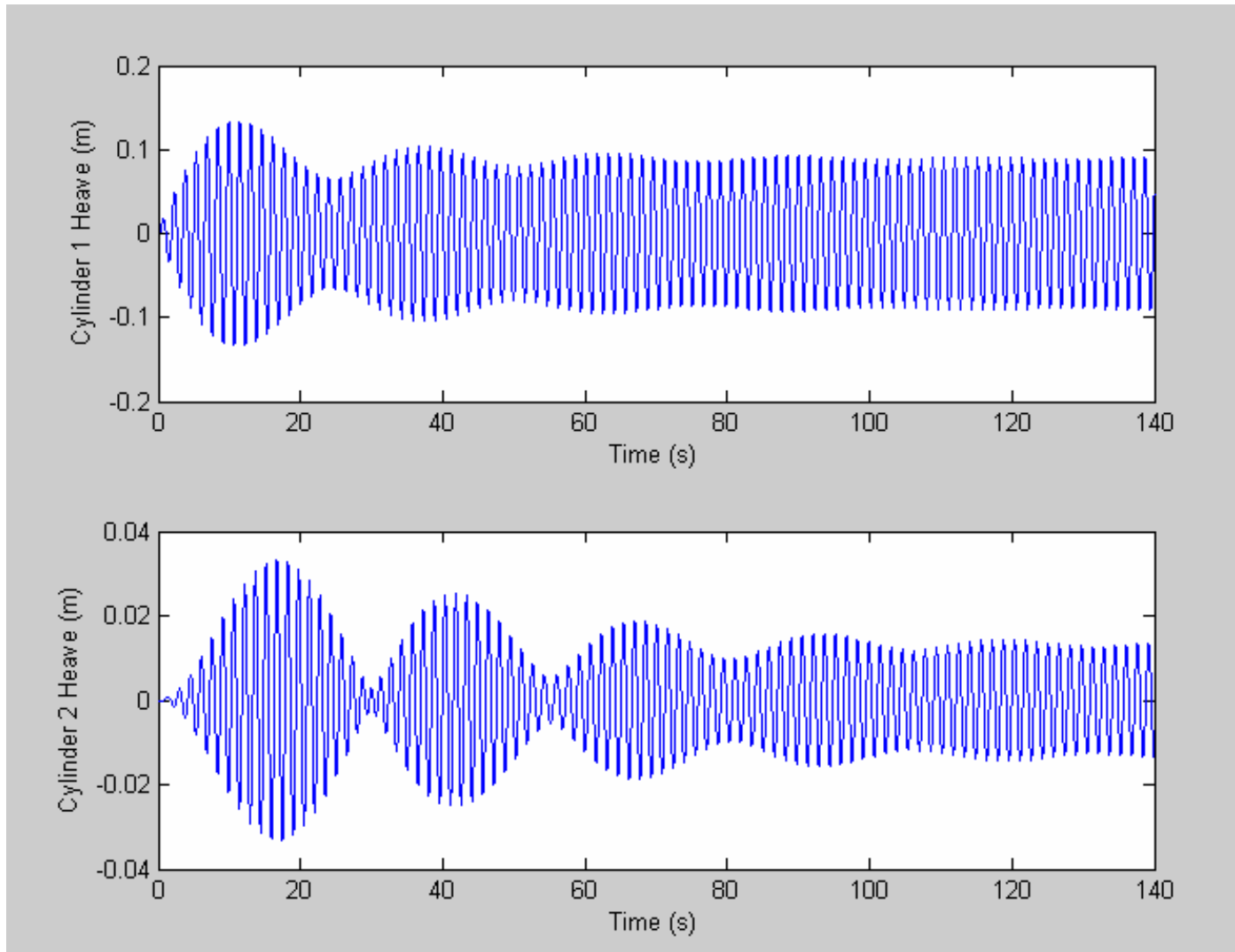
Simulink Model of the Two Interacting Cylinders



Animation of Interacting Cylinders



Motion of Interacting Cylinders



Conclusions and Further Work



- We are developing a fast and accurate hydrodynamic time domain array model.
- It will be embodied in a wave-to-wire model that integrates Lancaster control and Edinburgh generator models.
- Further work includes:
 - incorporation of regular and irregular incident waves.
 - testing of different WEC shapes and modes.
 - inclusion of non-linear effects.